

Graph Product Structure Theory

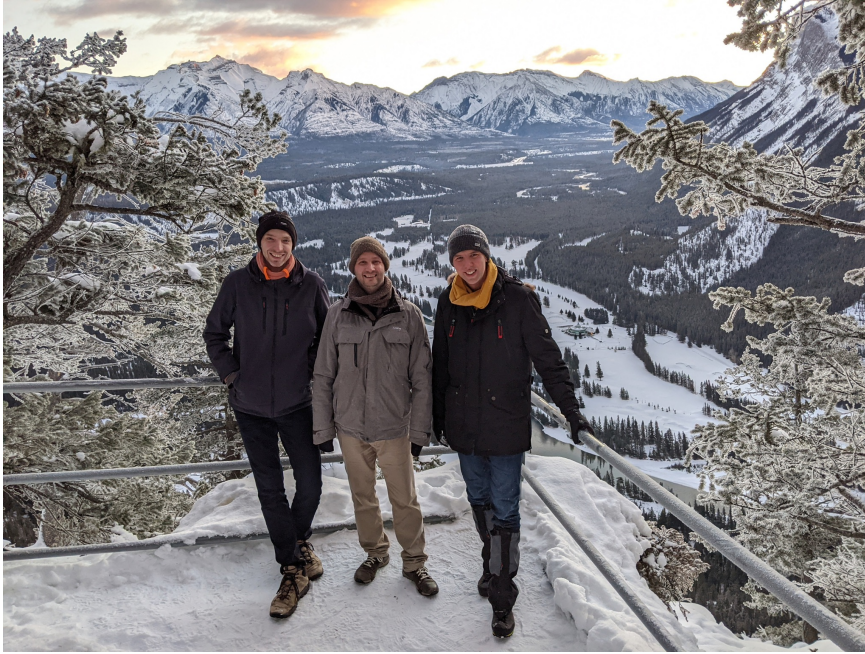


$$G \subseteq H \boxtimes P$$

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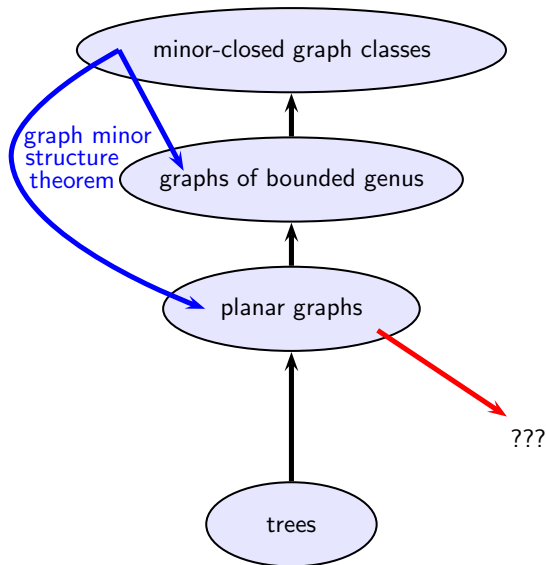
Ranking Graph Classes by Complexity

Simple

- ▶ paths (forests of paths)
- ▶ trees (forests)
- ▶ k -Trees (graphs of treewidth at most k)
- ▶ \vdots
- ▶ planar graphs
- ▶ \vdots
- ▶ proper-minor closed families
- ▶ \vdots
- ▶ bounded expansion
- ▶ \vdots
- ▶ all graphs

Complicated

structure of planar graphs



The Product Structure Theorem for Planar Graphs

Theorem (Dujmović-Joret-Micek-M^{Drin}-Ueckerdt-Wood 2019):

For every planar graph G , there exists a planar graph H of treewidth at most 8 and a path P such that G is a subgraph of $H \boxtimes P$.

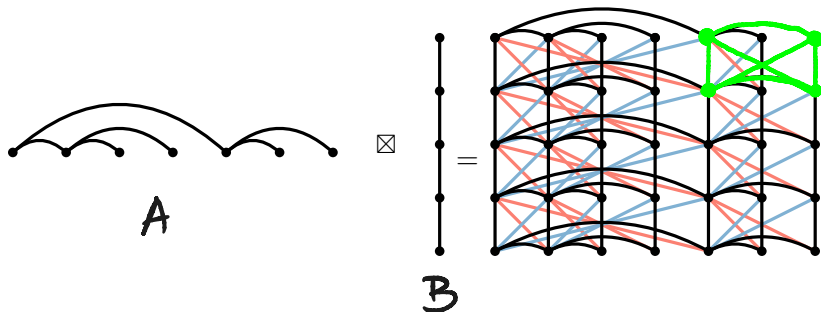
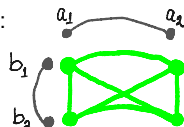
↳ simple treewidth 6

[Ueckerdt, Wood, Y, 2021]

The Strong Graph Product \boxtimes

For two graphs A and B , the *strong product* $A \boxtimes B$ is a graph:

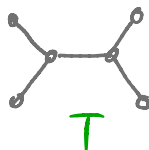
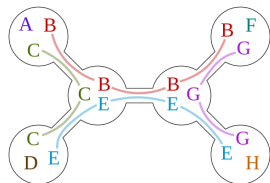
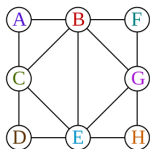
- ▶ $V(A \boxtimes B) := V(A) \times V(B)$
- ▶ (a_1, b_1) and (a_2, b_2) are adjacent if and only if:
 - ▶ $a_1 = a_2$ and $b_1 b_2 \in E(B)$;
 - ▶ $a_1 a_2 \in E(A)$ and $b_1 = b_2$; or
 - ▶ $a_1 a_2 \in E(A)$ and $b_1 b_2 \in E(B)$.



Treewidth

A *tree-decomposition* of a graph G represents each vertex as a subtree of a tree T so that the subtrees of adjacent vertices intersect in T

G



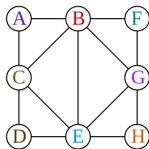
tree-decomposition
of G

[Images courtesy of Wikipedia]

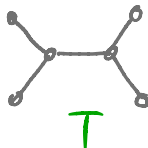
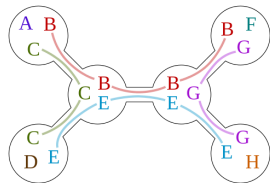
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width := maximum bag size - 1



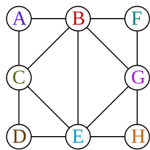
tree-decomposition
of G

[Images courtesy of Wikipedia]

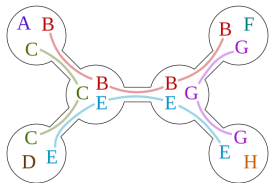
Treewidth

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G



width := maximum bag size - 1



T



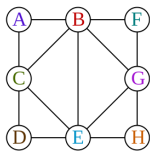
T

tree-decomposition
of G

[Images courtesy of Wikipedia]

Treewidth

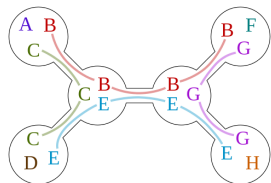
A *tree-decomposition* of a graph G represents each vertex as a subtree of a tree T so that the subtrees of adjacent vertices intersect in T



width := maximum bag size - 1

treewidth := min width of tree-decomposition of G

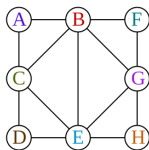
→ measure of how "tree-like" a graph is



[Images courtesy of Wikipedia]

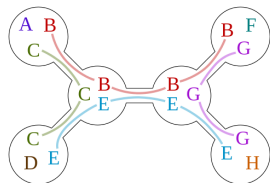
Treewidth

A *tree-decomposition* of a graph G represents each vertex as a subtree of a tree T so that the subtrees of adjacent vertices intersect in T



width $:=$ maximum bag size $- 1$

treewidth $:=$ min width of tree-decomposition of G

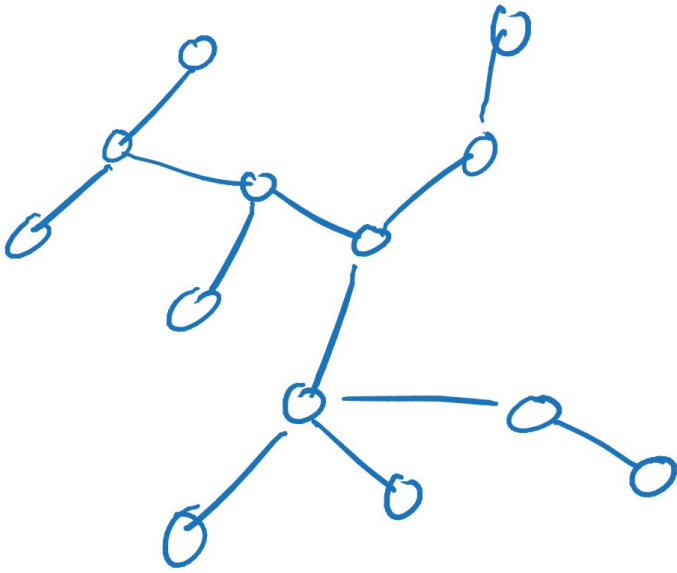


- trees?
- triangulations of polygons?
- grids?
- separators?

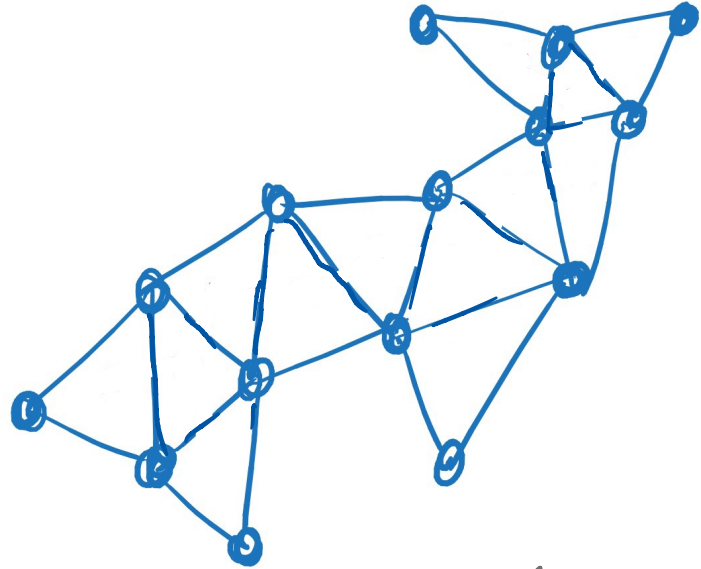
[Images courtesy of Wikipedia]

How do build tree-decomp

→ GOOD

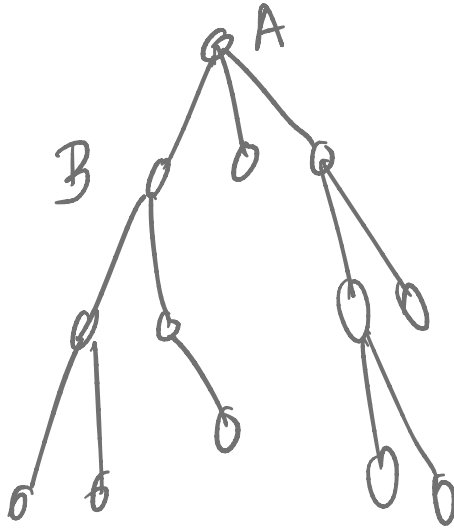


How would you
build a tree-decomp.
of this tree?

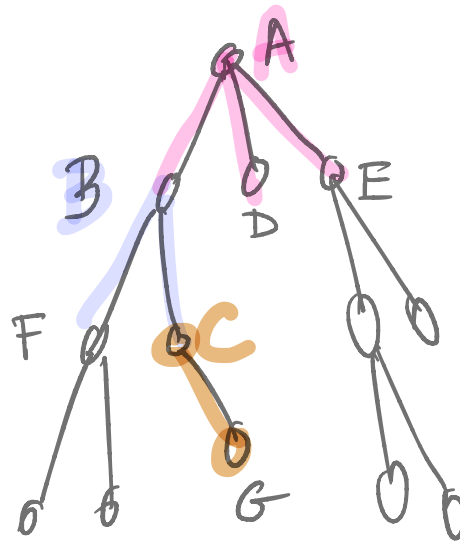
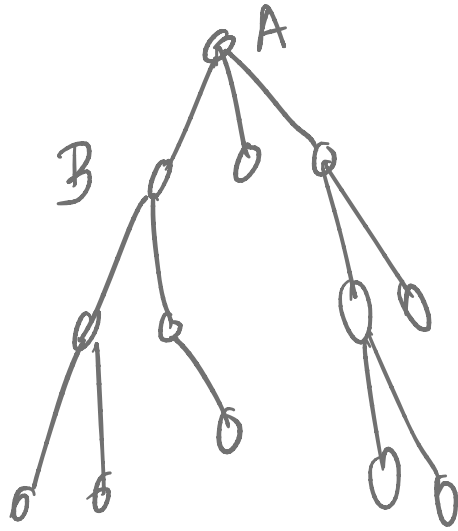


or this outerplanar
graph?

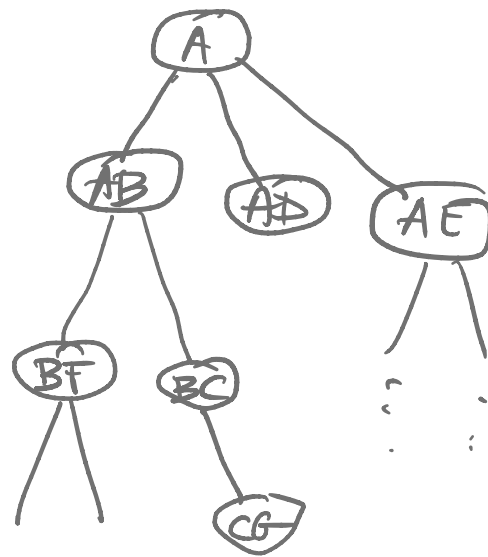
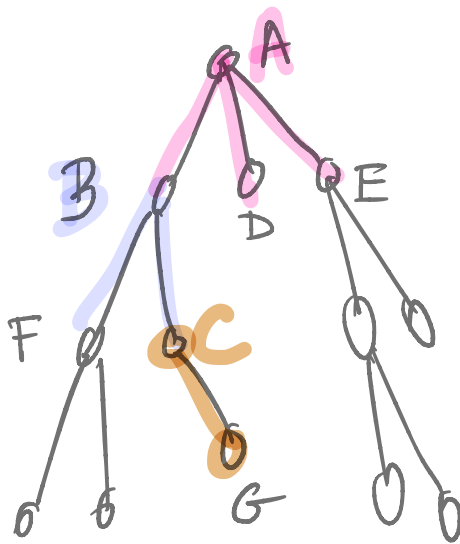
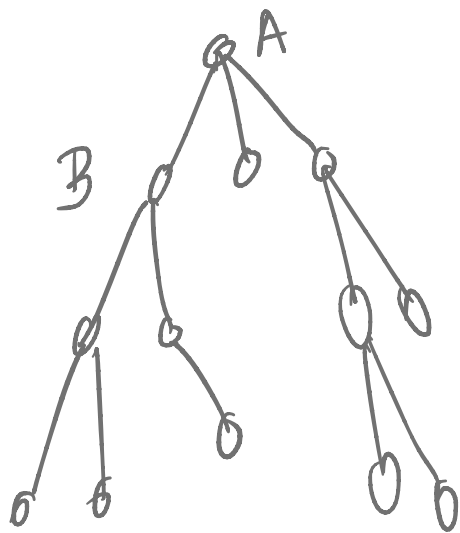
trees



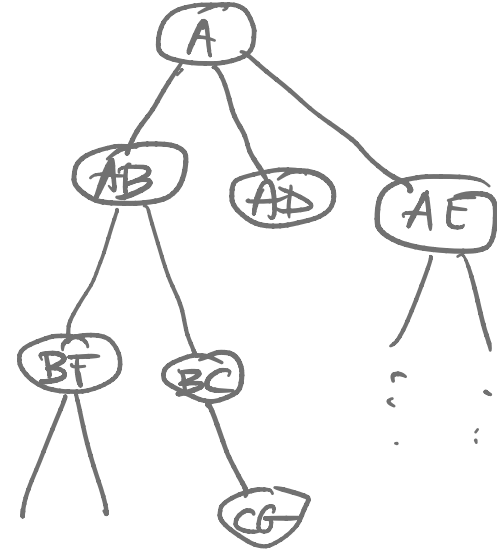
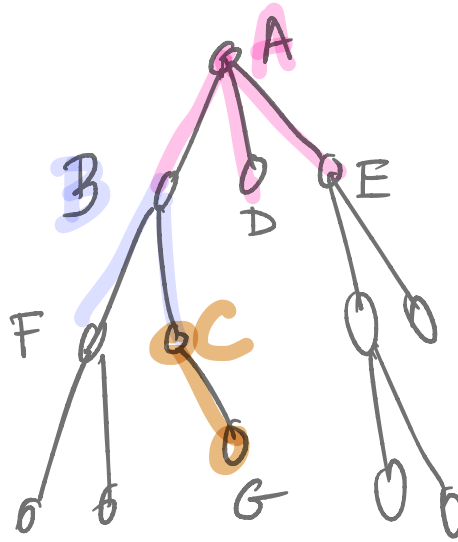
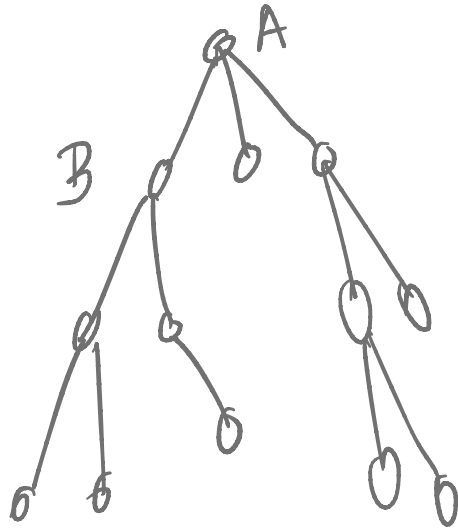
trees



trees



trees

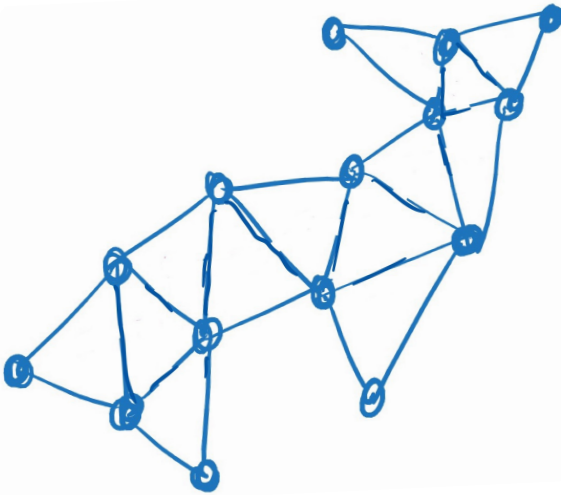


↓
width = 2

// Trees have width 1

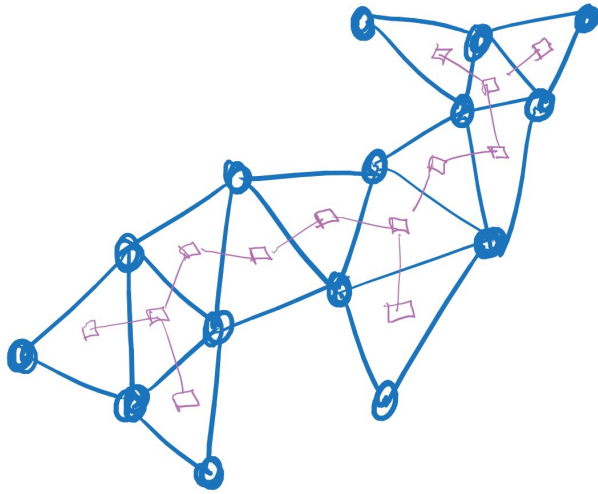
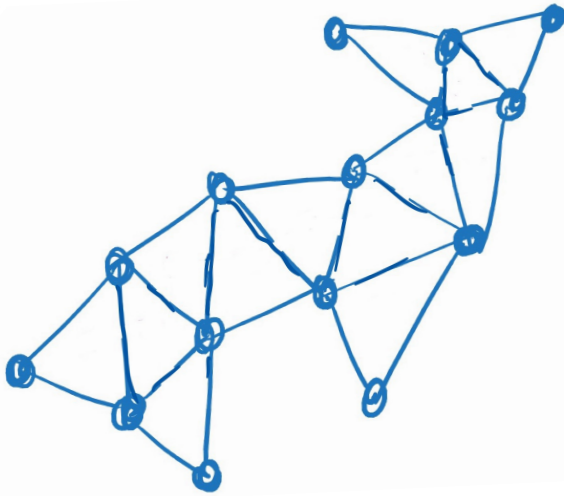
outerplanar graphs

↳ triangulations of polygons



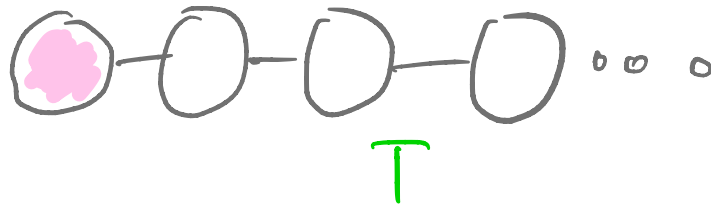
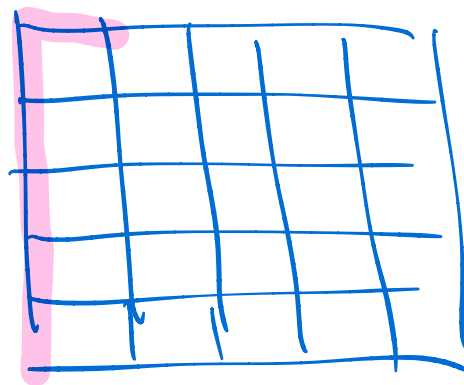
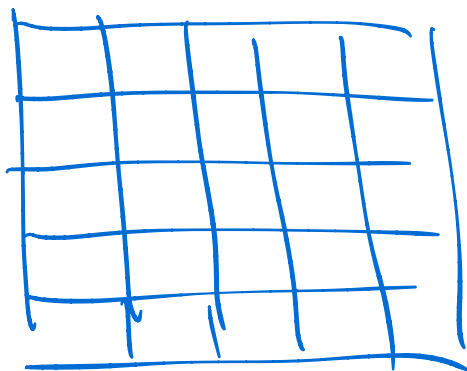
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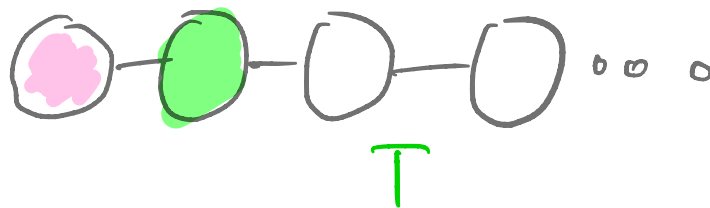
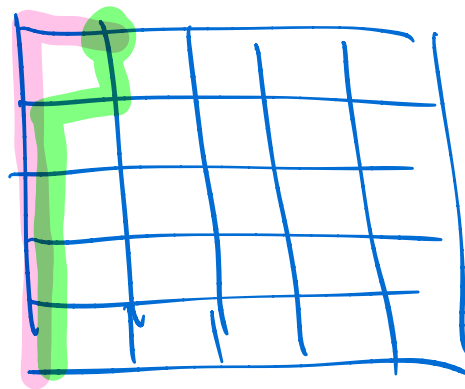
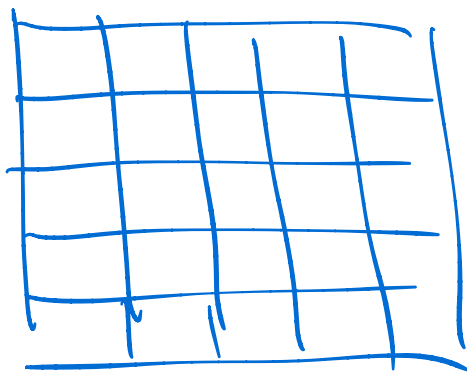


th Outerplanar graphs have treewidth 2.

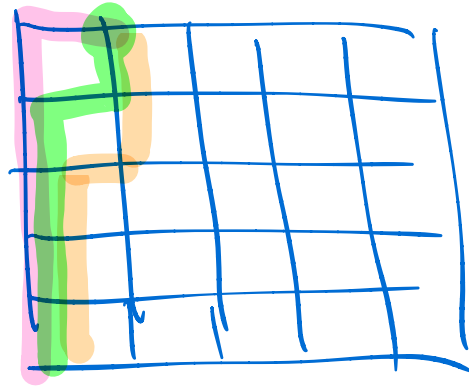
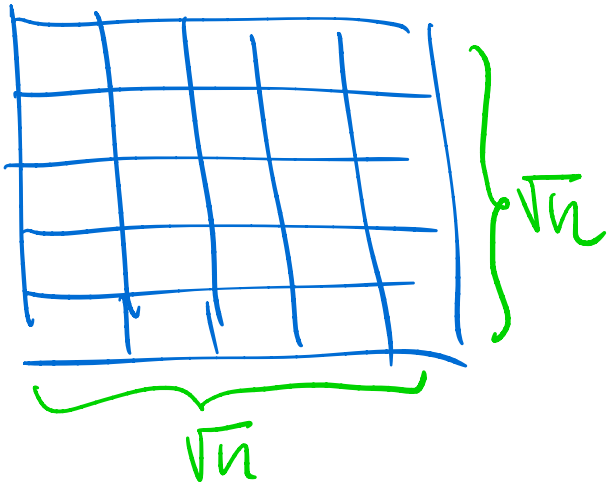
grids



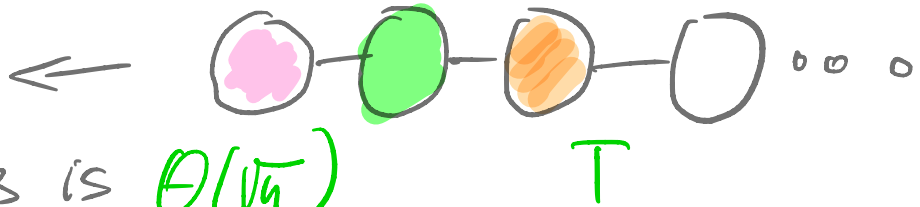
grids



grids



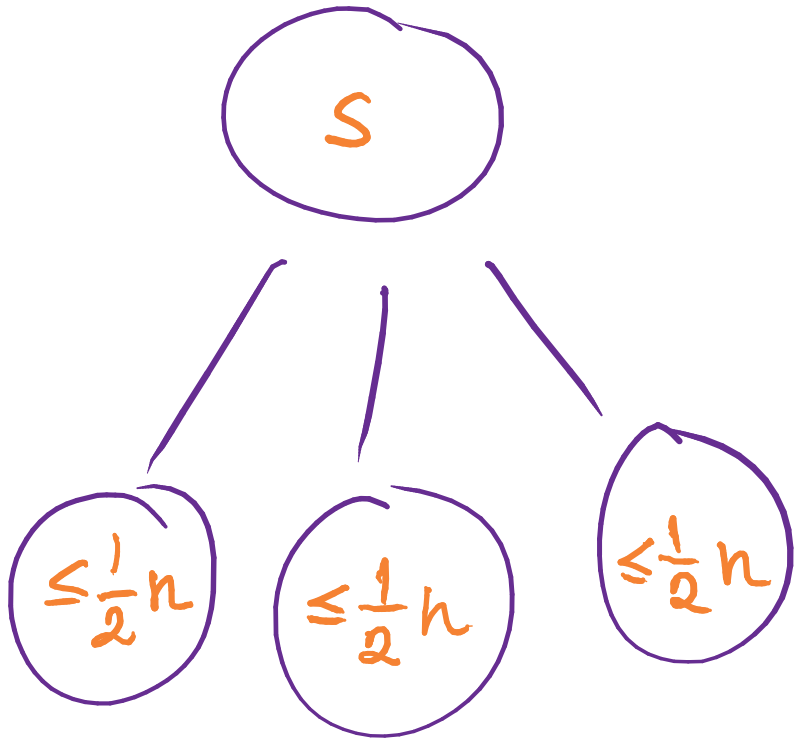
width $\Theta(\sqrt{n})$



Tree width of grids is $\Theta(\sqrt{n})$

CLASSICAL SEPARATORS

balanced $\alpha \in [\frac{1}{2}, 1)$



$$S \subseteq V(G)$$

s.t every connected component of $G - S$ has $\leq \frac{1}{2} |V(G)|$ vertices.

$|S|$:= size of separator

MANY APPLICATIONS

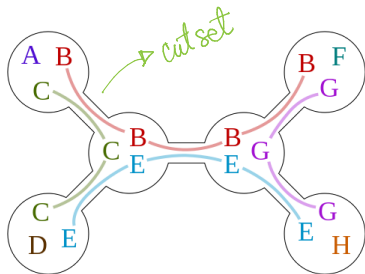
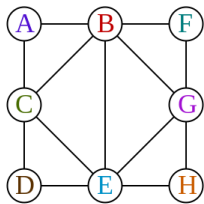
graphs with small separators

- ↳ parametrized (exact) algorithms
- ↳ approximation algorithms
(divide and conquer)

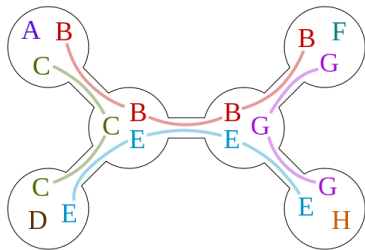
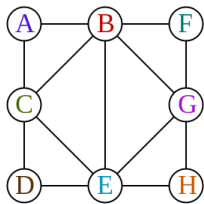
graphs with no small separators

- $km \geq \frac{n}{2}$
- expanders
(sparse graphs with high 'global' connectivity)

Where are the separators?



Where are the separators?



Robertson and Seymour:

balanced separators $\leq tw + 1$

↳ for weighted graphs too

Dvořák and Norin:

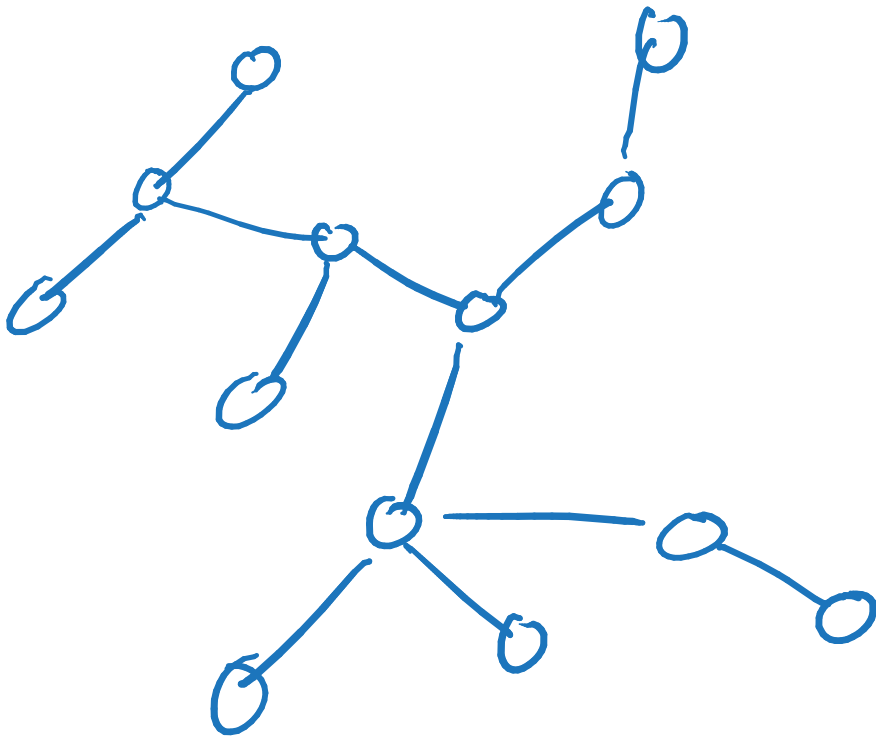
Reverse is true.

$$tw(G) \leq 105 \text{ sep}(G)$$

\Rightarrow Treewidth and separ. tied

Example : TREES

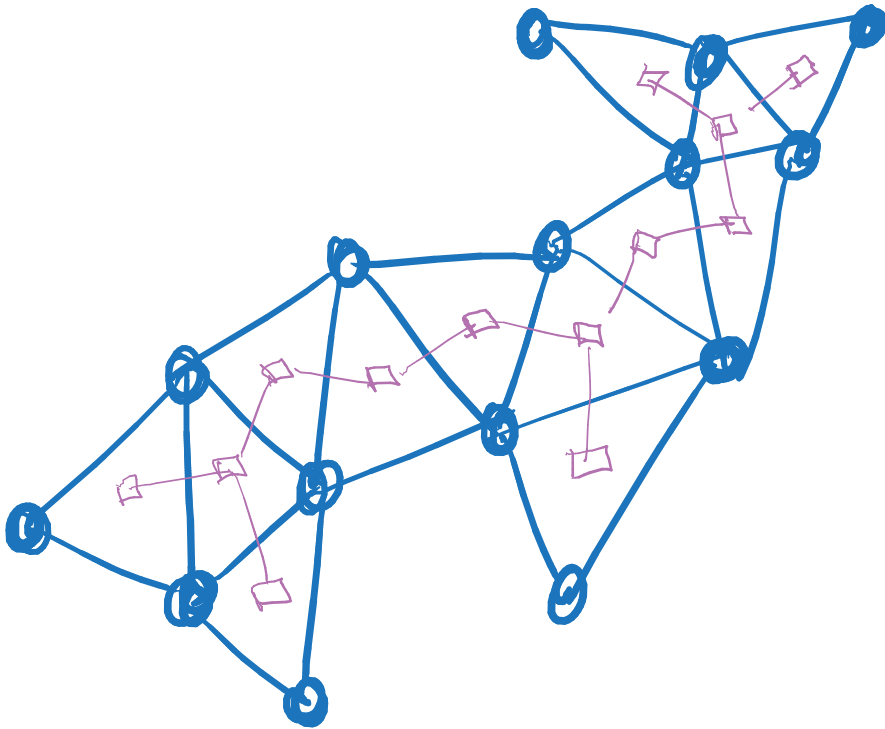
Th : Every tree has a separator of size 1.



Example : OUTERPLANAR

• outerplanar graph

Th : Every ~~tree~~ has a separator of size ~~1~~³.



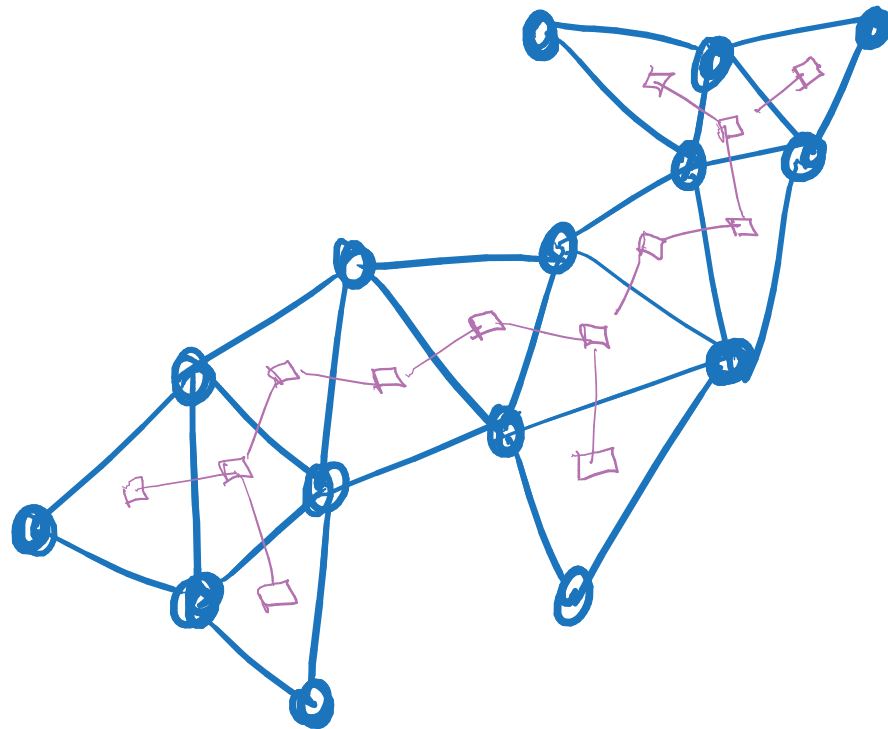
Example : OTHER

• outerplanar graph

Th :

Every ~~tree~~ has a separator of size ~~1~~.

3



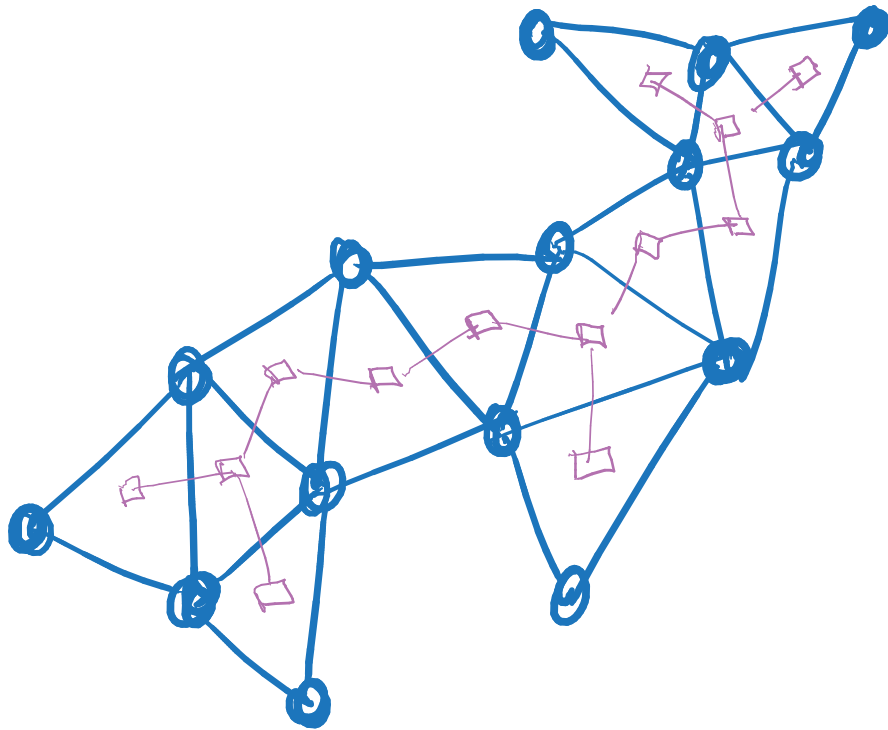
→ • series-parallel
too

Q : Do all planar graphs have constant size separators?

Example : OTHER

• outerplanar graph

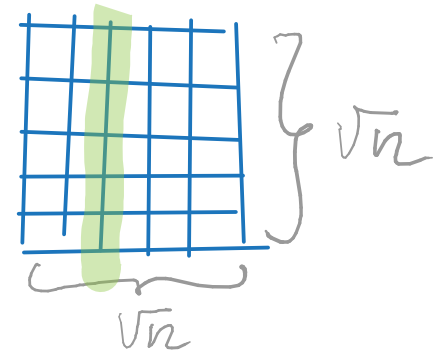
Th : Every ~~tree~~ has a separator of size ~~1~~.



→ • series-parallel
do

Q : Do all planar graphs have constant size separators?

NO



What about planar graphs?

Lipton & Tarjan '80s:

Planar graphs have $\Theta(\sqrt{n})$ separators.

→ bounded genus
↳ proper minor closed

Used extensively:

- PTAS alg $\begin{pmatrix} 1+\epsilon \\ 1-\epsilon \end{pmatrix}$
- EPTAS
- bidimensionality

→ does not help us though
e.g. nonrepetitive colourings,
guene layouts ...

The Product Structure Theorem for Planar Graphs

Theorem (Dujmović-Joret-Micek-M^{DEIN}-Ueckerdt-Wood 2019):

For every planar graph G , there exists a planar graph H of treewidth at most 8 and a path P such that G is a subgraph of $H \boxtimes P$.

↳ simple treewidth 6

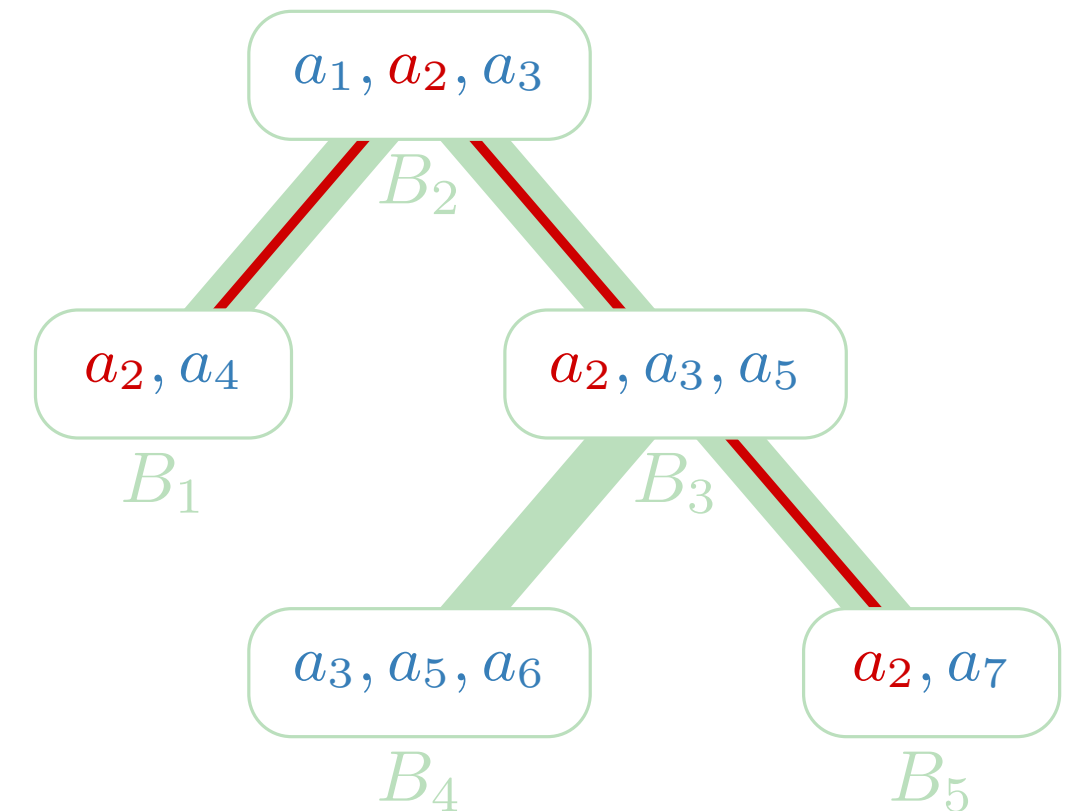
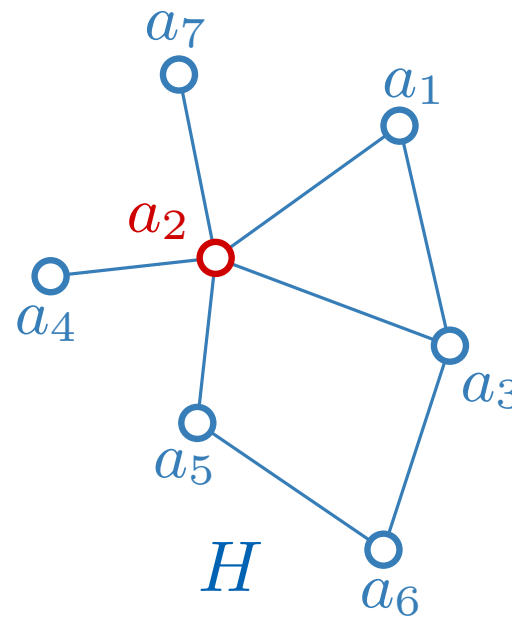
[Ueckerdt, Wood, Y, 2021]

Tree Decompositions

A **tree decomposition** of H are vertex sets (bags) B_1, B_2, \dots such that

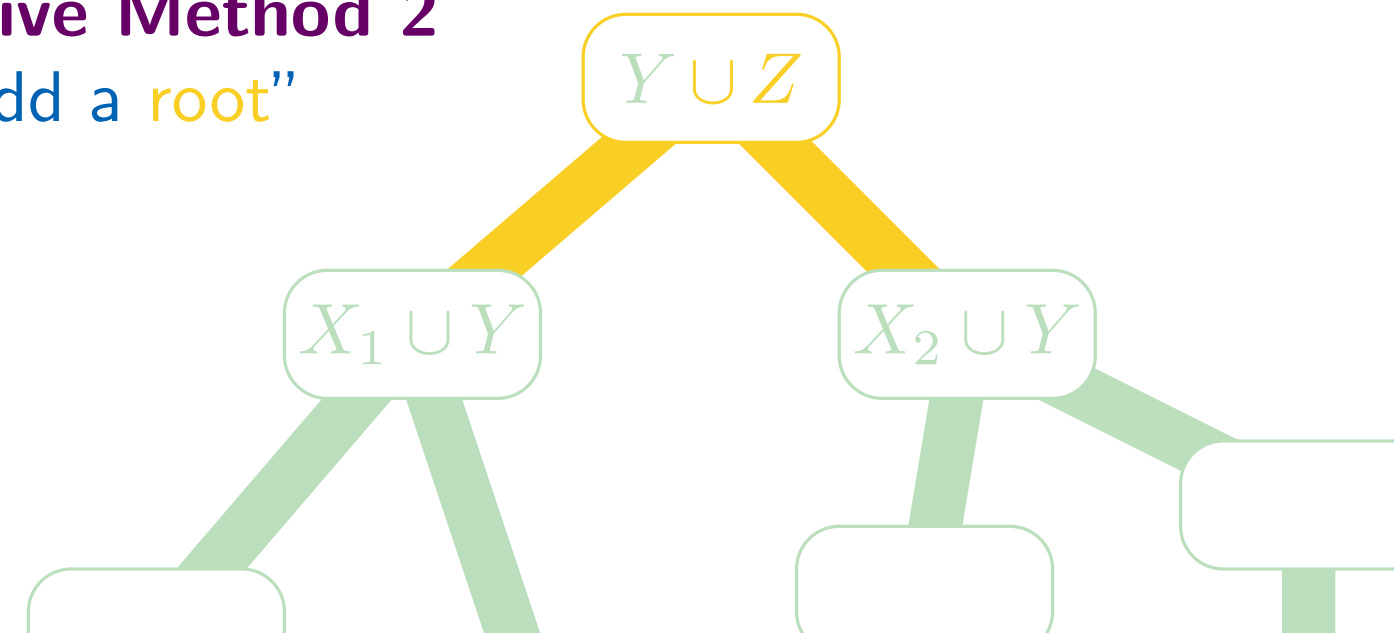
- ▷ B_1, B_2, \dots are the vertices of a tree
- ▷ $v \in V(H) \Rightarrow \{B_i \mid v \in B_i\}$ subtree
- ▷ $uv \in E(H) \Rightarrow \exists i : u, v \in B_i$

The **width** is the maximum size of a bag -1 .



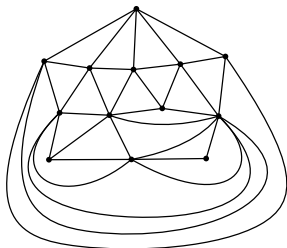
Inductive Method 1
“add a **leaf**”

Inductive Method 2
“add a **root**”



The Precursor

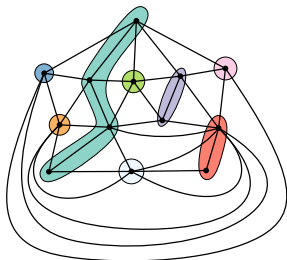
Theorem (Siebertz-Pilipczuk 2018): For any planar triangulation G , there exists a partition \mathcal{P} of $V(G)$ such that



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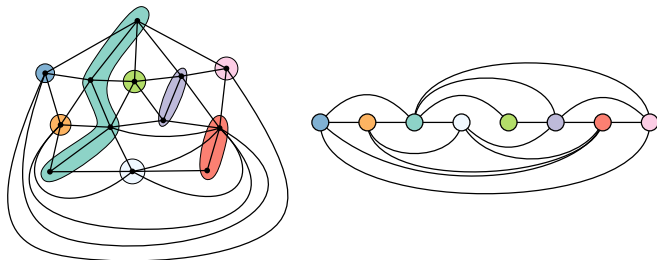
- ▶ Each part of \mathcal{P} induces a *geodesic* (shortest path) in G ; and



The Precursor

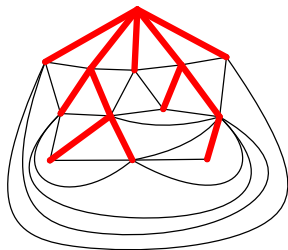
Theorem (Siebertz-Pilipczuk 2018): For any planar triangulation G , there exists a partition \mathcal{P} of $V(G)$ such that

- ▶ Each part of \mathcal{P} induces a *geodesic* (shortest path) in G ; and
- ▶ The quotient graph $H := G/\mathcal{P}$ has treewidth at most 8



Layered H -Partitions

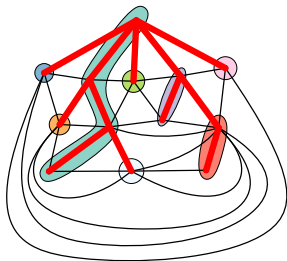
Theorem (Dujmović-Joret-Micek-M-Ueckerdt-Wood 2019):
For any planar triangulation G and any *breadth-first spanning-tree* T of G , there exists a partition \mathcal{P} of $V(G)$ such that



Layered H -Partitions

Theorem (Dujmović-Joret-Micek-M-Ueckerdt-Wood 2019):
For any planar triangulation G and any *breadth-first spanning-tree* T of G , there exists a partition \mathcal{P} of $V(G)$ such that

- ▶ Each part of \mathcal{P} induces a *vertical path* in T

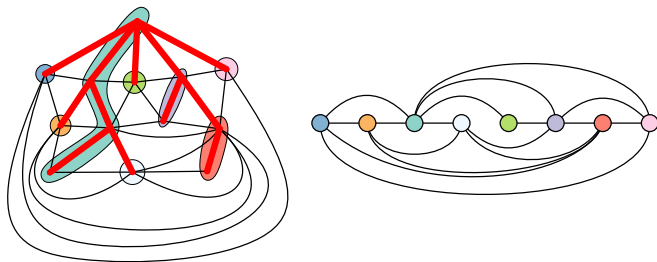


Layered H -Partitions

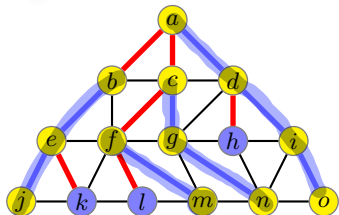
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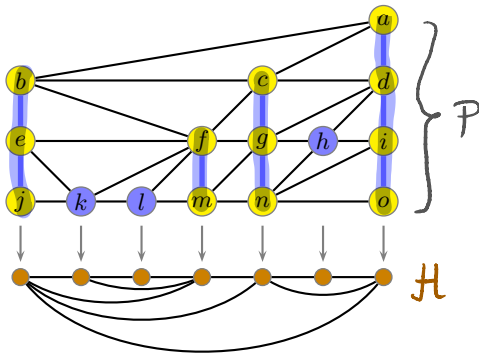
- ▶ Each part of \mathcal{P} induces a *vertical path* in T
- ▶ The quotient graph $H := G/\mathcal{P}$ has treewidth at most 8



Equivalence:



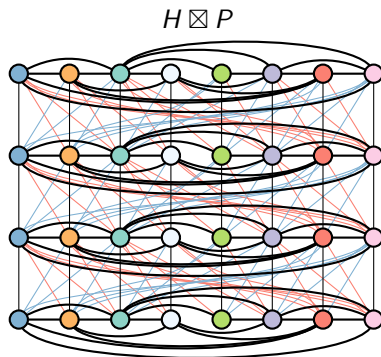
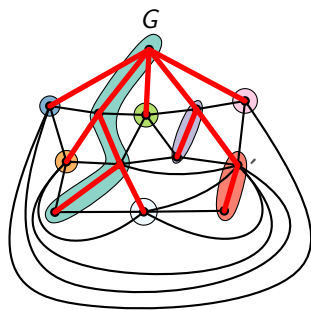
vertical
paths



$$G \subseteq H \boxtimes P$$

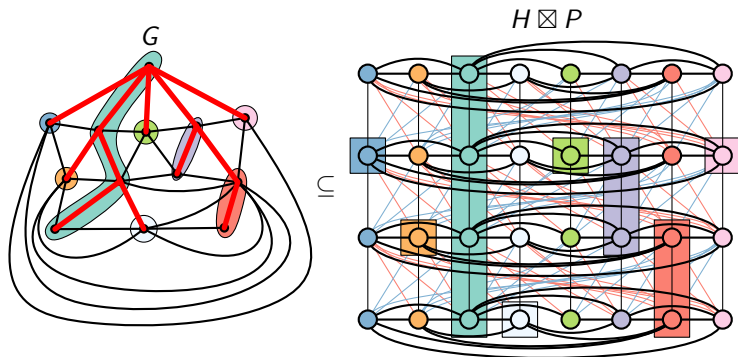
Equivalence

Vertical H -partition theorem and product structure theorem are equivalent:



Equivalence

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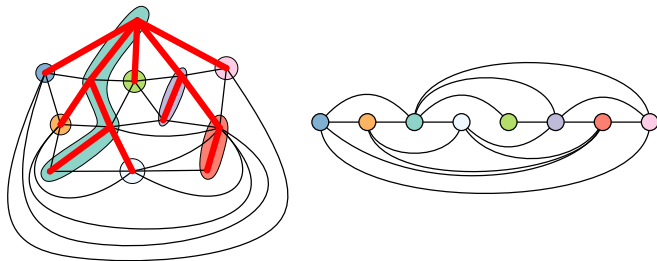


Layered H -Partitions

Theorem (Dujmović-Joret-Micek-M-Ueckerdt-Wood 2019):

For any planar triangulation G and any *breadth-first spanning-tree* T of G , there exists a partition \mathcal{P} of $V(G)$ such that

- ▶ Each part of \mathcal{P} induces a *vertical path* in T
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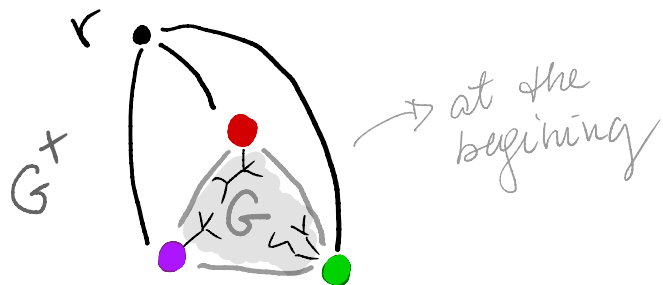
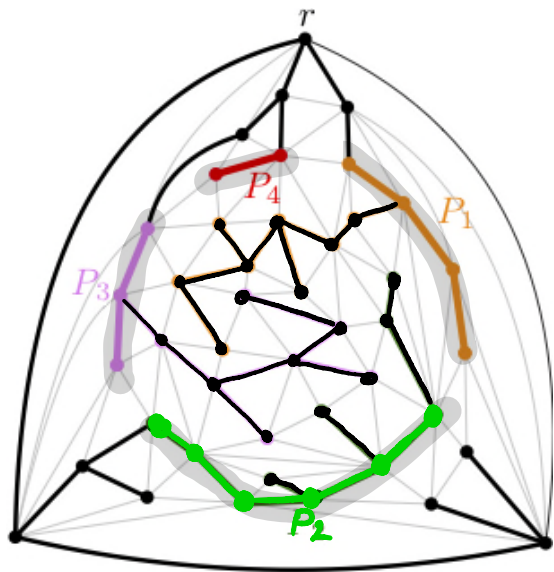


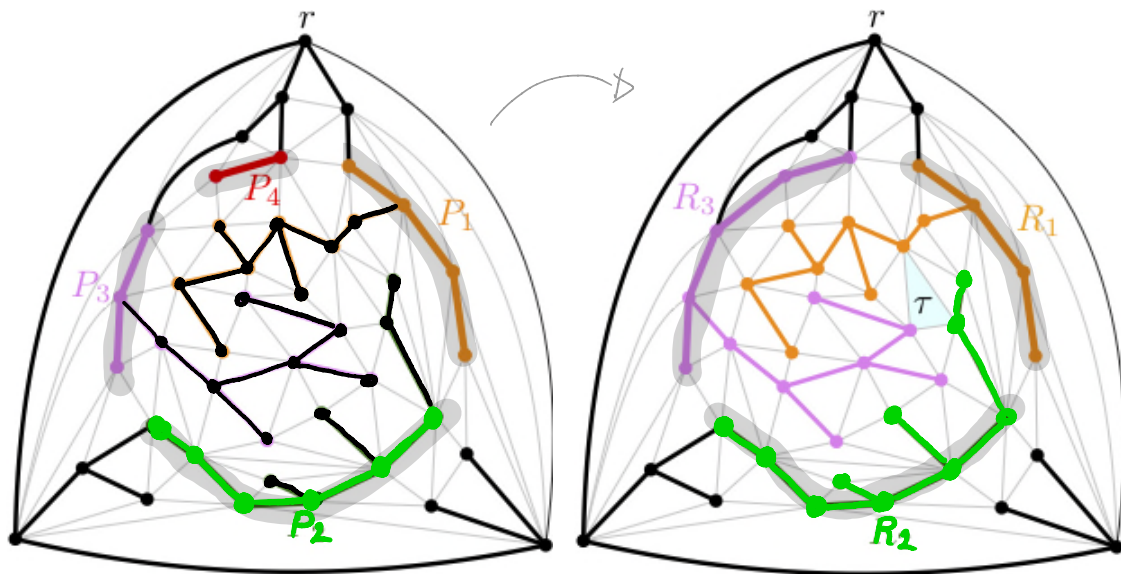
Proof: Partitioning Planar Graphs

Key lemma. Suppose

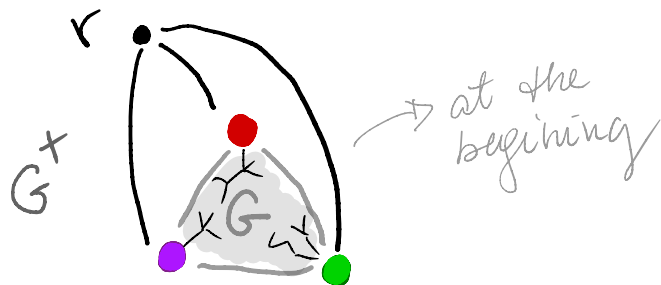
- G^+ plane triangulation
- T rooted spanning tree of G^+ with root on outer-face
- cycle C partitioned into vertical paths P_1, \dots, P_k , with $k \leq 6$
- G near-triangulation consisting of C and everything inside.

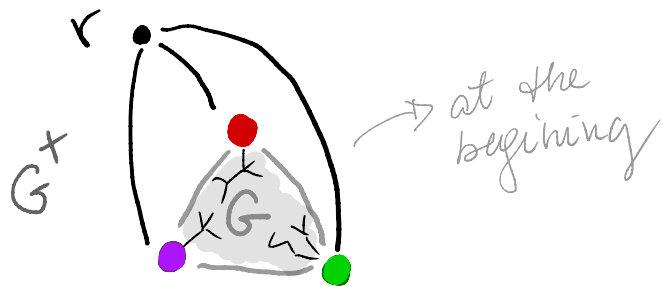
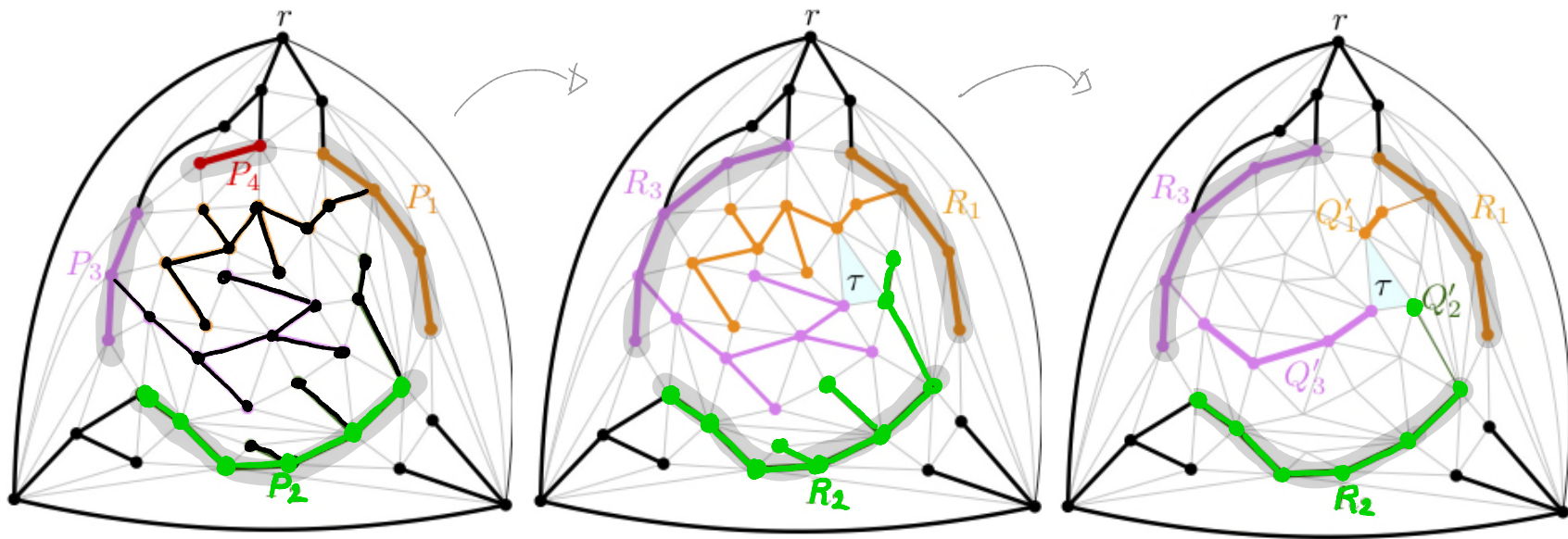
Then G has a partition \mathcal{P} into vertical paths where $P_1, \dots, P_k \in \mathcal{P}$
s.t. $= G/\mathcal{P}$ has a tree-decomposition in which every bag has size
at most 9 and some bag contains all vertices corresponding to
 P_1, \dots, P_k .

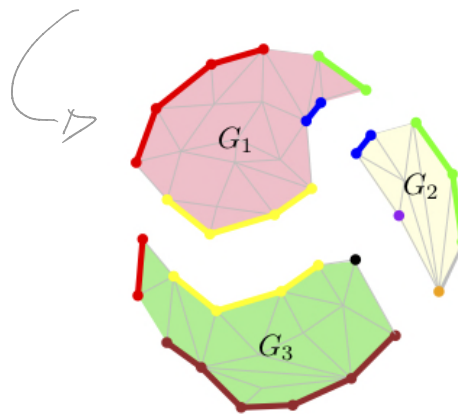
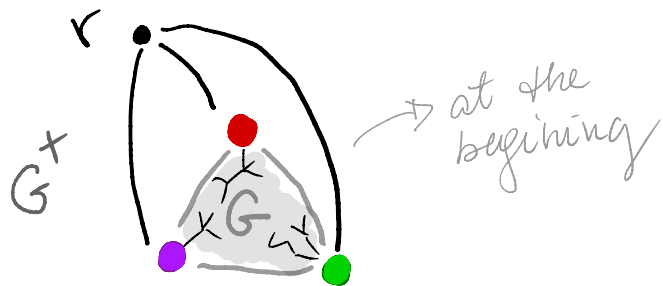
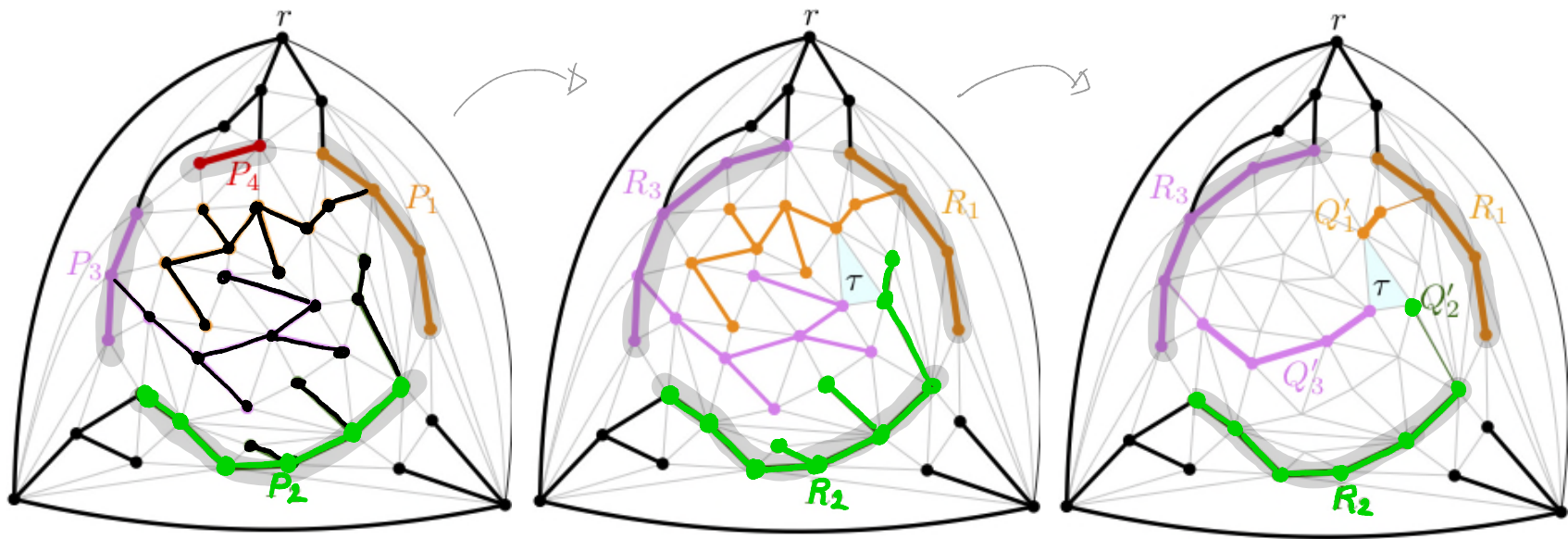




Sperner
lemma





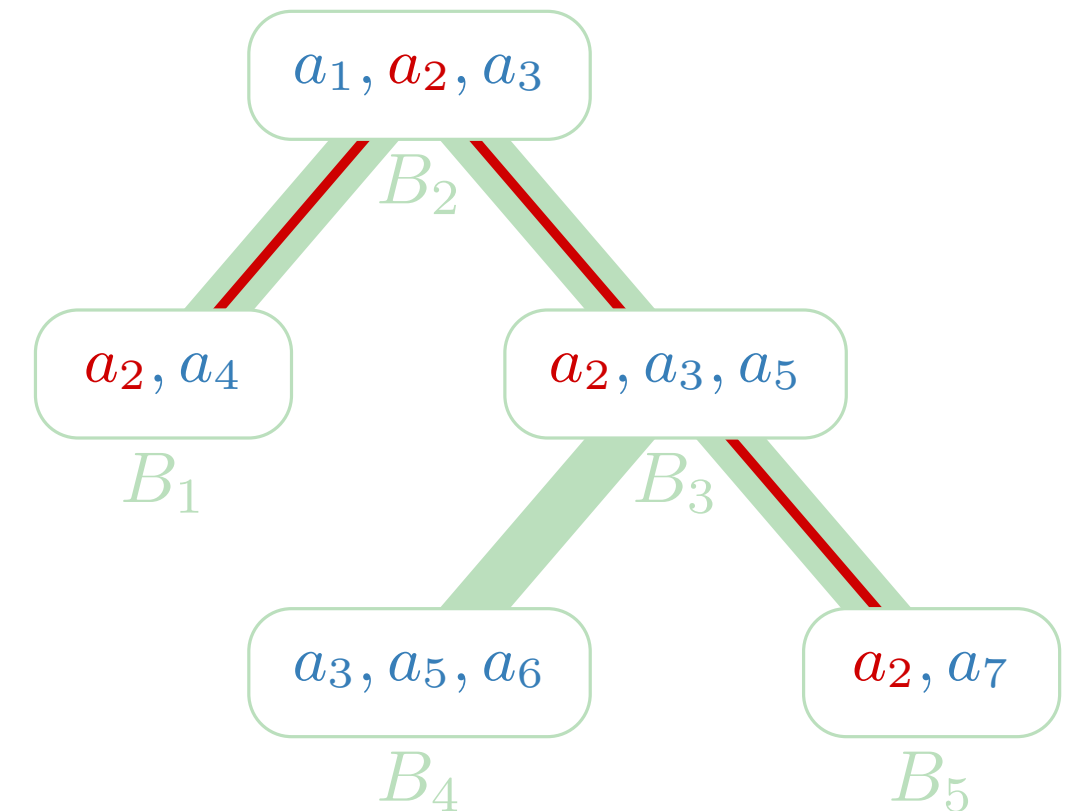
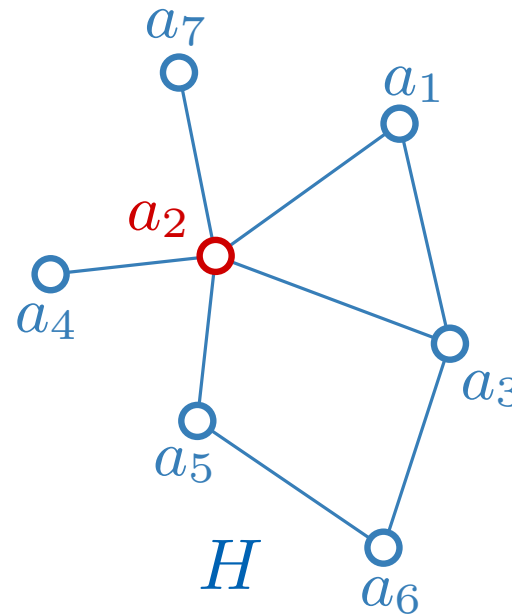


Tree Decompositions

A **tree decomposition** of H are vertex sets (bags) B_1, B_2, \dots such that

- ▷ B_1, B_2, \dots are the vertices of a tree
- ▷ $v \in V(H) \Rightarrow \{B_i \mid v \in B_i\}$ subtree
- ▷ $uv \in E(H) \Rightarrow \exists i : u, v \in B_i$

The **width** is the maximum size of a bag -1 .



Inductive Method 1
“add a **leaf**”

Inductive Method 2
“add a **root**”

